volume through which it propagates. To avoid significant pump depletion, the total energy in the laser beams must be much greater than that in the plasma wave.

The problem of producing plasmas (particularly with a cross magnetic field) with densities between $10^{16} < n_s < 10^{20} \text{ cm}^{-3}$ and with the required length and homogeneity will also require considerable attention. At high intensities that are necessary in this scheme, the requirement that plasma frequency be exactly equal to the difference frequency may be relaxed, but this issue needs careful investigation.

**Prospects for ultrahigh energies**

High-phase velocity space charge waves in a plasma have the potential for producing the high accelerating gradients that are necessary for a new generation of particle accelerators. Whether this scheme can be used to accelerate particles to ultrahigh energies depends on how well the phase stabilization (Surfatron) scheme can be made to work in practice. Particular problems are pump depletion, filamentation of the laser and injected particle beams, and the effect of self-generated magnetic fields on the accelerating particles.

On the positive side, the Surfatron scheme would produce a compact accelerator with a high quality beam. The energy spread, $\Delta \gamma / \gamma$ would be small because half of the injected particles quickly form accelerating 'buckets' that are narrow in phase space near the equilibrium point. In the wave frame this is where $\gamma m B$ is equal to the local longitudinal electric field. Thus all the particles gain energy at nearly the same rate, the one given by equation (4). The bunch length of the final beam as well as $\Delta \gamma / \gamma$ is thus expected to be extremely small, as shown in Fig. 5.

The number of accelerated particles $N$ can be estimated from the consideration of the energy balance:

$$N = 2 \times 10^{16} \frac{\text{laser energy (kJ)}}{\text{particle energy (GeV)}} \epsilon \alpha \lambda \mu \sqrt{n_{16}}$$

where factor $\alpha$ is the ratio of particle energy to wave energy.

The zero-order motion of the particles in the Surfatron scheme is approximately a straight line, and thus synchrotron radiation loss turns out not to be a problem. The radiation loss due to high-order bounce motion and due to oscillation in the laser field, as well as other loss mechanisms such as Coulomb scattering and bremsstrahlung radiation, are also not thought to be serious problems.

Finally, the acceleration scheme is still at an embryonic stage for a reliable estimate to be made of its potential total efficiency from wall power to beam power. The severest limitation, one that is common to all laser acceleration schemes, is the a.c.-to-laser beam efficiency. If we optimistically assume this to be 10% then using our simulations as a guide we may be able to achieve a total efficiency between 10^{-3} and 10^{-4}.

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### Is there a climatic attractor?

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*Much of our information on climatic evolution during the past million years comes from the time series describing the isotope record of deep-sea cores. A major task of climatology is to identify, from this apparently limited amount of information, the essential features of climate viewed as a dynamic system. Using the theory of nonlinear dynamic systems we show how certain key properties of climate can be determined solely from time series data.*

**Experimental data** have essentially two roles in the process of modelling. First, they parameterize the equations postulated by the model. Second, they set constraints to be satisfied by the model. For instance, a reasonable model of Quaternary glaciations should reproduce the general aspects of a palaeo-temperature time series as deduced from ice or deep-sea core data and, in particular, should exhibit the characteristic time scales of 100,000, 41,000 and 22,000 yr (ref. 1). In either case, however, the information drawn from the data will remain essentially one-dimensional. Thus, starting from the time series of a certain variable one may construct a power spectrum or a histogram which, despite their interest, do not provide any hint about the additional variables that may affect the evolution. We show here that experimental data contain far richer information which, independent of any particular model, can be used to 'resolve' the multi-variable dynamics of a system starting from a time series pertaining to a single variable.

We should first comment on the status of a time series from the standpoint of the theory of dynamical systems. Let $X_0(t)$ be the time series available from the data, and $(X_k(t),)$ where $k = 0, 1, \ldots, n - 1$, the full set of variables actually taking part in the dynamics. $(X_k)$ is expected to satisfy a set of first-order nonlinear equations, whose form is generally unknown but which, given a set of initial data $(X_0(0))$, will produce the full details of the system's evolution. It is instructive to visualize this evolution in an abstract multi-dimensional space spanned by these variables, the phase space. An instantaneous state of the system becomes a point, say $P$, in this space, whereas a sequence of such states followed as time varies defines a curve, the phase space trajectory (see Fig. 1). As time grows and transients die out, the system is expected to reach a state of permanent regime, not necessarily time-independent. In phase space, this will be reflected by the convergence of whole families of phase trajectories towards a subset of phase space (C in Fig. 1), such that the system subsequently remains trapped therein.

We refer to this invariant set as the attractor.

The interest of the phase space description of a system lies primarily in the fact that the nature of the attractors provides extensive information on the time behaviour of the variables and on the nature of their coupling. For instance, a point
attractor (point 0 in Fig. 2a, b) implies that the transient-free
behaviour of the system will be time-independent. In addition,
if the attractor is approached in the way shown in Fig. 2a the
transients will die out monotonically, whereas a spiral approach
like that in Fig. 2b indicates that transients perform damped
oscillations. An attractor in the form of a closed curve (C in
Fig. 1) implies, on the other hand, that the system will perform
sustained oscillations in time with an intrinsically-determined
period and amplitude. Finally, multiperiodic motions with
incommensurate frequencies are represented in phase space by
high-dimensional attracting toroidal surfaces. In each of the
above cases, the character of the attractor also gives an indication
of the minimum number of variables that should be involved
in the description. Thus, for the zero-dimensional attractors of
Fig. 2 (d = 0) we need, respectively, at least one variable (n = 1)
for Fig. 2a and two variables (n = 2) for Fig. 2b. For the one-
dimensional attractor of Fig. 1 (d = 1) we need at least two
variables (n = 2), and for the simplest quasi-periodic
phenomenon we need at least a two-dimensional torus (d = 2)
embedded in a three-dimensional phase space (n = 3).

So far we have argued in terms of attractors which are points,
lines or surfaces or, in more technical terms, smooth topological
manifolds characterized by an integer dimensionality. In recent
years, it has been firmly established that geometrical objects
exist which are not topological manifolds. Such constructions,
which have a non-integer dimensionality, are known as fractals.
The theory of dynamical systems and some experimental results
from fluid dynamics and chemical kinetics provide us with many
examples of fractal attractors. The importance of the latter
steps from the fact that they model irregular, time-dependent
phenomena, characterized by two features, both of which are
shared by the climatic system: a marked sensitivity to initial
conditions; and the appearance of large dispersions from a mean
motion similar to a stochastic process, even though the underly-
ing dynamics is perfectly deterministic. Note that the dimension-
ality of an attractor, fractal or smooth, is bound to be a number
smaller than the number of variables present in the evolution.

Climatic attractor

We shall establish the existence of an attractor associated with
the long-term climatic evolution of the past million years and
determine its dimensionality. Knowing the characteristics of this
climatic attractor automatically gives us information on the
minimum number of variables that must be introduced into the
description.

Our starting point is the oxygen isotope record obtained from
the equatorial Pacific deep-sea core V28–238 (refs 4, 5), which
is one of the best climatic records available, because the sediment
accumulated at a fairly regular rate.

Let \( X_0(t) \) be the corresponding time series. Because the variables \( \{X_k(t)\} \) satisfy a set of first-order differential equations,
successive differentiation in time reduces the problem to a single
(generally highly nonlinear) differential equation of \( n \)th order

\[ X_0(t), X_0(t + \tau), \ldots, X_0(t + (n-1)\tau) \quad (1) \]

for one of these variables. Thus, instead of \( X_0(t), k = 0, 1, \ldots, n-1 \), we may consider \( X_0(t) \), the variable supplied
by the time series data, and its \( n-1 \) successive derivatives
\( X_0^{(k)}(t), k = 1, \ldots, n-1 \), to be the \( n \) variables of the problem
spanning the phase space of the system. Now, both \( X_0 \) and its
derivatives can be deduced from the single time series pertaining
to \( X_0(t) \), as provided by the data. We see, therefore, that, in
principle we have sufficient information at our disposal to go
beyond the one-dimensional space of the original time series
and to unfold the system's dynamics into a multidimensional
phase space.

Actually, as suggested originally by Ruelle, instead of \( X_0(t) \)
and \( X_0^{(k)}(t) \) it will be easier to work with \( X_0(t) \), and the set of
variables obtained from it, by shifting its values by a fixed lag \( \tau \). We, therefore, consider from now on the phase space defined
by the variables:

\[ X_0(t), X_0(t + \tau), \ldots, X_0(t + (n-1)\tau) \quad (1) \]

For a typical choice of \( \tau \) these variables are expected to be
linearly independent, and this is all one needs to define properly
a phase space. A simple example illustrating how an unshifted
function can give rise to a linearly independent one by a simple
shift is provided by the polynomials \( X_0(t) = t^2 \), \( X_0(t + \tau) = t^2 + 2t\tau + \tau^2 \). These two functions are indeed independent, as
the second polynomial contains terms of first and zero degree in $t$, which are absent in the first one.

Before describing the procedure that will enable us to obtain quantitative information on the nature of the climatic attractor and, in particular, on its dimensionality we present, in Fig. 3, a characteristic view of this object in a three-dimensional phase space. This view clearly exhibits the complexity of the underlying motion. However, the data are too coarse to draw any conclusion from this figure alone. It will be our task to characterize the complexity of the dynamics more sharply and, in particular, to assess its similarities and differences with random noise. Note that similar phase portraits have been constructed from experimental data pertaining to chemical kinetics.

**Analytical procedure**

We now describe briefly a recently proposed procedure\(^\text{11,12}\) which allows the identification of some salient features of the phase space portrait of a dynamical system. Consider a set of $N$ points on an attractor embedded in a phase space of $n$ dimensions, obtained from a time series:

$$
X_0(t_0), \ldots, X_0(t_N)
$$

$$
X_0(t_0 + \tau), \ldots, X_0(t_N + \tau)
$$

$$
\vdots
$$

$$
X_0(t_0 + (n-1)\tau), \ldots, X_0(t_N + (n-1)\tau)
$$

For convenience we introduce a vector notation: $X_i$ which stands for a point of phase space whose coordinates are $[X_0(t_i), \ldots, X_0(t_i + (n-1)\tau)]$.

A reference point $X_i$ from these data is now chosen and all its distances $|X_i - X_j|$ from the $N - 1$ remaining points are computed. This allows us to count the data points that are within a prescribed distance, $r$, from point $X_i$. Repeating the process for all values of $i$, one arrives at the quantity

$$
C(r) = \frac{1}{N^2} \sum_{i,j=1}^{N} \theta(r - |X_i - X_j|)
$$

where $\theta$ is the Heaviside function, $\theta(x) = 0$ if $x < 0$, $\theta(x) = 1$ if $x > 0$. The non-vanishing of this quantity measures the extent to which the presence of a data point $X_i$ affects the position of the other points. $C(r)$ may thus be referred to as the (integral) correlation function of the attractor.

Suppose that we fix a given small parameter $\epsilon$ and we use it to define the site of a lattice which approximates the attractor. If the latter is a line, the number of data points within a distance $r$ from a prescribed point should be proportional to $r^d$. If it is a surface, this number should be proportional to $(r/\epsilon)^2$ and, more generally, if it is a $d$-dimensional manifold it should be proportional to $(r/\epsilon)^d$. We expect, therefore, that for $r$, relatively small $C(r)$ should vary as

$$
C(r) = r^d
$$

In other words, the dimensionality $d$ of the attractor is given by the slope of the log $C(r)$ versus log $r$ in a certain range of values of $r$:

$$
\log C(r) = d \log r
$$

This property remains valid for attractors of fractal dimensionality.

The above results suggest the following algorithm (a similar procedure has also been proposed in the context of fluid dynamics):

1. Starting from a time series, we can construct the correlation function, equation (3), by considering successively higher values of the dimensionality $n$ of phase space.

2. Deduce the slope $d$ near the origin according to equation (5) and see how the result changes as $n$ is increased.

3. If $d$ reaches a saturation limit beyond some relatively small $n$, the system represented by the time series should possess an attractor. The saturation value $d_s$ will be regarded as the dimensionality of the attractor. The value of $n$ beyond which saturation is observed will provide the minimum number of variables necessary to model the behaviour represented by the attractor.

**Application to climatic data**

This procedure has been applied to the analysis of the data pertaining to core V28-238. Figure 4 gives the dependence of log $C(r)$ versus log $r$ for $n = 2$ to $n = 6$. We see that there is indeed an extended region over which this dependence is linear, in accordance with equation (5). Figure 5 (points in circles) shows that the slope reaches a saturation value at $n = 4$, which is about $d_s = 3.1$. The same plot also shows the way in which $d$ varies with $n$ if the signal considered is a Gaussian white noise: there is no tendency to saturate. In fact, in this case $d$ turns out to be equal to $n$. It should be emphasized that the above results are independent of the choice of the time lag $\tau$, provided that the latter is of the order of magnitude of the times scales pertaining to the long-term climatic evolution, and the linear independence of the variables is secured.

The existence of a climatic attractor of low dimensionality shows that the main feature of long-term climatic evolution may be viewed as the manifestation of a deterministic dynamics,
involving a limited number of key variables. The fact that the attractor has a fractal dimensionality provides a natural explanation of the intrinsic variability of the climatic system, despite its deterministic character. Moreover, it suggests that despite the pronounced peaks of spectra in the frequencies of the orbital forcings, the actual behaviour is highly non periodic. A new interpretation of variance spectra of the ice volume record is, therefore, necessary.

Conclusion
We have identified a number of intrinsic properties of the climate assuming it to be dynamical system, using only the time series obtained from the data.

Our results do not anticipate the validity of any particular model of climatic evolution. Rather, they set a number of constraints that should be satisfied by a model. In particular, they suggest that models involving four variables could already provide a description of the salient features of the system.

Our approach could be applied to many other problems in which naturally occurring complex systems are probed through time series. Within the context of atmospheric physics and climatology, one important example is the blocking transition. Another promising field of application are biological rhythms like the heart beat or the electroencephalogram. In the long run, it may be hoped that fractal dimensionality could become for such systems a useful characterization of their specificity as well as a measure of their complexity.

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Structure of the nucleosome core particle at 7 Å resolution

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The crystal structure of the nucleosome core particle has been solved to 7 Å resolution. The right-handed B-DNA superhelix on the outside contains several sharp bends and makes numerous interactions with the histone octamer within. The central turn of superhelix and H3·H4 tetramer have dyad symmetry, but the H2A·H2B dimers show departures due to interparticle associations.

The nucleosome is the primary repeating unit of DNA organization in chromatin. Extensive digestion of chromatin with micrococcal nuclease releases the nucleosome core, a small, well-defined particle which has been crystallized. The particle mass (≈ 206 kilodaltons) is equally distributed between 146 (± 2) base pairs (bp) of DNA and an octamer formed by two each of the histone proteins, H2A, H2B, H3 and H4 (the outer histone H1 and the linker DNA having been removed during nuclease digestion). The crystals first obtained were of limited order and gave a picture of the particle to 20 Å resolution. We later prepared better crystals which diffracted to about 5 Å, having a single particle in the asymmetric unit. We describe here the three-dimensional structure of the nucleosome core particle at 7 Å resolution determined by X-ray diffraction and multiple isomorphous replacement. This advance was achieved by improved diffractometry, control of the crystal unit cell parameters by adjustment of hydration, and derivatives prepared from multi-heavy-atom cluster compounds.

The nucleosome core crystals have previously been investigated by several structural methods. Electron microscopy and X-ray diffraction techniques were initially used to obtain electron density maps in the principal projections, suggesting that the particle had the shape of a disk 57 Å thick and 110 Å in diameter. The DNA appeared to be wound around the histone core in 1.8 turns of a flat superhelix with a pitch of 28 Å. Using neutron diffraction in conjunction with contrast matching, the DNA and protein components were seen as separate densities in projections at 25 Å resolution. The three-dimensional shape of the octamer alone was determined to a resolution of 20 Å by image reconstruction from electron micrographs of negatively stained, ordered aggregates. The assignment of histone locations on the resulting low-resolution map relied on DNA-histone and histone-histone (for references, see ref. 12) proximities obtained from chemical cross-linking experiments, and the neutron experiments fixed the orientation of the DNA superhelix on the octamer. The suggested division of the octamer into two H2A·H2B dimers residing on opposite faces of a H3·H4 tetramer agrees well with the pattern of dissociation found in earlier physicochemical studies. The tetramer (proteolysed) and octamer have also been crystallized in the absence of DNA, but structures have not yet been reported.

The electron density map at the higher resolution of 7 Å described here reveals many new structural features. The DNA is not bent uniformly into the superhelix, but exhibits several regions of right bending or possible kinking, adjacent to points of substantial contact with histones H3 and H4. The histone-DNA interactions occur on the inside of the superhelix; the protein density does not seem to embrace the outside of the